eLM.SigmaTrac.01 - 07: SigmaTrac eLearning/Sales



NOTE: This test covers the topics in eLM.SigmaTrac.01, eLM.SigmaTrac.02, eLM.SigmaTrac.03, eLM.SigmaTrac.05, eLM.SigmaTrac.06, eLM.SigmaTrac.07.

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Name of Y	askawa Rep:				
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Option 1: Option 2: Receiving You may I during clas	E-mail the answers a Your Score review your answers as, you will receive your siste enrollment test,	kawa Technica nd all contact in s only if a passi our score as soon	I Training Services at (847) 887-7185. Info below to training@yaskawa.com. Ing score is received. When the test is taken in as it can be graded. When taken as a CLEP test be automatically emailed to you when the test is		
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Overview

1.	What is the maximum accelerate A. 1 G C. 3G B. 2 G D. 4 G		Trac linear motor E. 5 G	?
2.	What parameter must be set in A. Pn280 (Linear Scale Pitch) B. Pn202 (Electronic Gear Rat		-	n using Sigma Trac? Output Resolution)
3.	What rotary switch must be set when using Sigma Trac? A. Switch 1	to position "3" in B. Switch 2		GDG amplifier C. Switch 3
Sig	ma Trac Design			
4.	Which constant should be used A. KT B. KM		competing linear KF	motors? D. KL
5.	Which are benefits of caged bat A. Better lubrication retention B. Less noise	ll bearing technol	logy? C. Longer life D. All of the abo	ve
6.	Is a serial converter built into the when using Sigma Trac? A. Built In	ne Sigma Trac de	sign, or is it neces B. Order One	sary to order one
7.	What is the pitch of the Renisha A. 78 nanometers B. 20 microns	aw linear encoder	r scale used with S C. 20 nanometer D. 78 microns	_
8.	What is the highest resolution p A. 78 nanometers B. 20 microns C. 20 nanometers	oossible with Sigi	na Trac? D. 78 microns E. 8192 counts p	per revolution
9.	What is the purpose of Yaskaw A. Creates a patented magnetic B. Cancels the force of magne C. Reduces cogging force D. Allows Sigma Trac to take	c monopole tic attraction bety	veen the iron core	and magnet track

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Sigma Trac vs. Ballscrew

- 10. Of the two types of ballscrews, which has the best performance?
 - A. Rolled
- B. Ground
- C. Ball Bearing
- D. Recirculating
- 11. Why can it be a problem to have a ballscrew positioning system with long stroke?
 - A. Torque is limited due to the diameter of the screw.
 - B. Speed is limited due to the resonant frequency.
 - C. Backlash is increased due to the bandwidth
- 12. Which is true about the initial purchase price of a precision ground ballscrew positioning system vs. Sigma Trac?
 - A. The precision ground ballscrew system is 20% more expensive than Sigma Trac.
 - B. The Sigma Trac is \$20 more expensive than the precision ground ballscrew system.
 - C. The Sigma Trac is 20% more expensive than the precision ground ballscrew system.
 - D. Both systems cost about the same
- 13. What is the bandwidth of the Sigma Trac?
 - A. 5-15 kHz
- B. 1.6 GHz
- C. 40 Hz
- D. 60 Hz
- 14. Which of the following are benefits to using Sigma Trac instead of a precision ground ballscrew positioning system?
 - A. Lower backlash, power loss, and maintenance
 - B. Higher rigidity and bandwidth
 - C. Higher speed, acceleration, resolution, and accuracy
 - D. Higher machine throughput and machine life
 - E. All of the above

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Sigma Trac Technology

- 15. There are many mechanical parts in a linear motor system, but a linear motor technically consists of what **two** parts?
 - A. Linear encoder and magnet track
 - B. Moving coil and magnet track
 - C. Linear bearings and moving coil
 - D. Linear bearings and magnet track
 - E. All of the above
- 16. What types of Yaskawa linear motors are available?
 - A. G,F,T
 - B. F,L,H
 - C. C,L,R
 - D. C,I,T
 - E. R,N,T
- 17. What sets the coreless G-Type apart from the others?
 - A. Sub Teeth technology and lowest cost
 - B. Highest acceleration for light loads
 - C. Highest power density and force output
 - D. High cogging force and low resolution
- 18. What sets the flat iron core F-type linear motor apart from the others?
 - A. Sub-teeth technology and lowest cost
 - B. Highest acceleration for light loads
 - C. Highest power density and force output
 - D. High cogging force and low resolution
- 19. What sets the balanced iron core T-type linear motor apart from the others?
 - A. Sub-teeth technology and lowest cost
 - B. Highest acceleration for light loads
 - C. Highest power density and force output
 - D. High cogging force and low resolution
- 20. What linear motor is used in the Sigma Trac?
 - A. Coreless G-type
 - B. Flat Iron Core F-type
 - C. Balanced Iron Core T-type

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Sigma Trac Myths

- 21. Why isn't the Sigma Trac as expensive as it may seem to be?
 - A. The initial purchase price for a Sigma Trac is actually less than a comparable ground ballscrew system.
 - B. Manufacturers and distributors are offering mail-in rebates on Sigma Trac products.
 - C. Greater initial cost is offset by ease of installation and maintenance, and performance benefits.
- 22. Why doesn't Sigma Trac jump during initialization?
 - A. Sigma Trac does a very slow initialization move that is hardly noticeable.
 - B. Initialization is not necessary because Sigma Trac linear motors use an absolute encoder
 - C. Sigma Trac uses Hall-Effect sensors to detect the magnetic pole location at power up.
 - D. Sub-teeth technology cancels the cogging force, manifested as a jumping motion.
- 23. Which are valid methods to control the transfer of heat to the payload?
 - A. Use a more efficient linear motor coil
 - B. Use thermal insulation
 - C. Use air or liquid cooling
 - D. All of the above
- 24. What is true about Sigma Trac?
 - A. The iron core is not attracted to the magnet track
 - B. The iron core can accelerate light loads faster than a coreless motor
 - C. Sigma track can achieve position stability in the nanometer range